

# **Antenna Tracking Chain**







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### Introduction

- ECA is a significant actor since more than 20 years in supply of Tracking Chains and products.
  - CTR70: Monopulse or Monoscan Tracking Receiver
  - DTC: Range of indoor / outdoor down converters (L, S, C, X and Ku Band) specially designed for CTR70 tracking receivers.
  - STR Step Track Receiver or Beacon receiver.

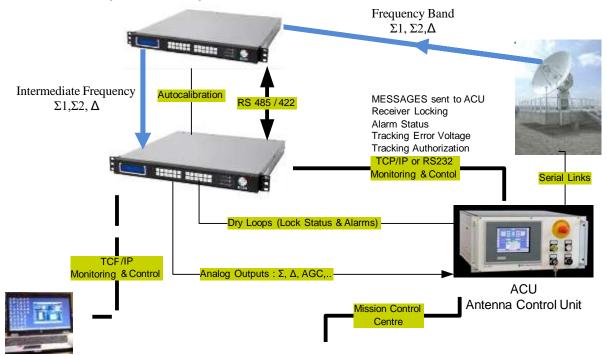






### **Tracking System Overview**

 ECA Group system is composed of a tracking receiver and a tracking converter fully managed through the tracking receiver (CTR70).









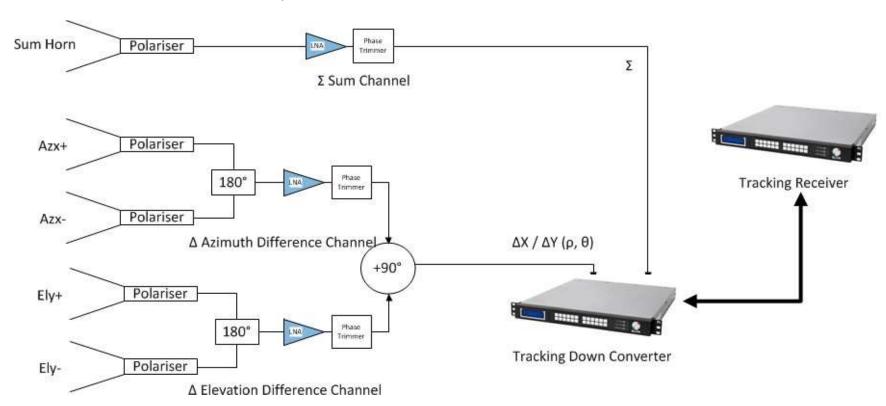
- ECA monopulse tracking receivers provide antenna control unit with high accuracy pointing instructions (analog and / or digital information).
- The CTR70 receiver has multipurpose modulation capabilities and can be set-up either in coherent mode or non coherent mode.
- Our different models (2, 3 channels) are suited to different kind of feeds:
  - Linear or circular polarization.
  - No multiplexing (no deterioration of the signal to noise ratio)
  - Error phase variations tolerant thanks to local or remote adjustment.
  - Capability for setting differential phase and amplitude between channels.
- "Auto-Calibration mode": This function provides the tracking chain with a long term stability on the differential phase & amplitude between channels. This function is only available with ECA Group DTC.
- Autophasis Function which enables the alignment of the Mono-pulse Tracking system in terms of phase







- CTR 70B 2 Channels Monopulse Tracking
  - Feed delivers 2 signals : ∑, Δ (ρ, θ)

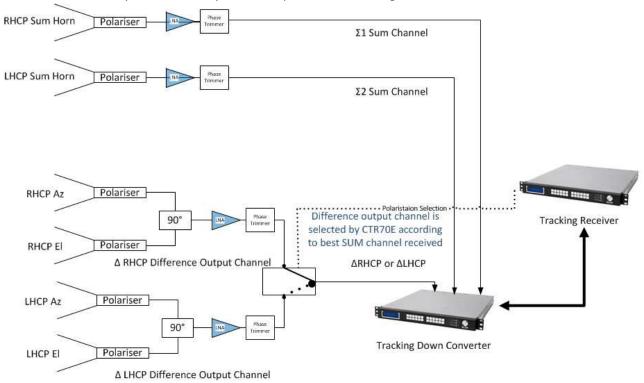








- CTR 70E: 3 Channels Monopulse Tracking
  - Feed delivers 3 signals : ( $\Sigma$ 1,  $\Sigma$ 2, Δ) CTR70E enables tracking either in RHCP or LHCP polarization
    - **Auto-diversity function**: Based on AGC value, the best receiving SUM channel signal (either RHCP or LHCP difference channel) is manually or automatically selected to perform the tracking.

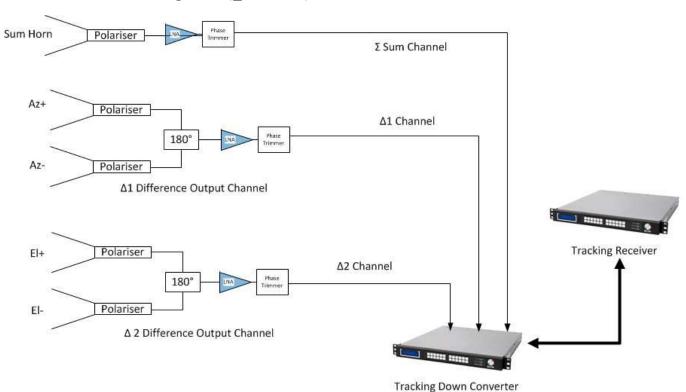








- CTR 70F: 3 Channels Monopulse Tracking
  - Feed delivers 3 signals : (Σ, Δ 1, Δ2)









## Tracking Receiver Main Features

### Common Tracking receivers features

#### Input

Nominal carrier frequency : 70 MHz

Input signal bandwidth : 5MHz max. (coherent mode)

Sum channel dynamic range: - 100 dBm to -10 dBm

Error channel level at error signal maximum : from 5 to 25 dB below sum

channel

Input noise spectral density (max level) : - 100 dBm/Hz

Minimum signal/Noise density: 8 dB in the loop bandwidth (coherent)

Or 3 dB above threshold (non coherent)

Maximum input signal level: + 13 dBm without permanent damage Input signal modulation: PM or FM/ MPSK/ Spread Spectrum

#### **Coherent tracking mode**

PLL loop bandwidth : 10, 30, 100, 300, 1000 and 3000 Hz

Damping factor :  $0.7 \pm 0.2$ 

Anti side band limits : Max PM index modulation 2 rad

Acquisition time (ASB OFF) on search range of + 150 kHz without noise:

Loop bandwidth Time to lock: 1 kHz : 0,1 sec

300 Hz : 0,6 sec 30 Hz : 4,3 sec 10 Hz : 375 sec

AGC time constant: 10 ms for monopulse / 30 ms monoscan

#### Non-coherent tracking mode

Selectable IF bandwidths : 50 kHz, 150 kHz, 500 kHz, 1.5 MHz, 5 MHz Selectable IF threshold level : from -10 dBm to -100 dBm by 1 dB step

#### Search frequency range

Acquisition range (for both coherent and no coherent mode) is

configurable from +/-1 kHz to +/-1.5MHz in 1 kHz step.

Center Sweep frequency : ±1500 kHz selectable 1 kHz step







## Tracking Receiver Main Features

### Common Tracking receivers features

#### Output to servo control unit

Output bandwidth: According to integration time

Output level adjustable : up to  $\pm$  10 V with the gain and

± 5 V offset adjustment on X and Y

Output impedance :  $1K\Omega$  (Typical value)

Integration time : 1, 10, 100, 1000 ms

APA output : Available when there is no alarm on Tracking

Chain and when receiver is locked

Auto calibration reference between the DTC unit and the receiver is carried

out 5 sec. after lock and after every X minutes: Differential phase stability :  $\pm$  5°

Amplitude stability: ± 1 dB versus time/dynamicrange

#### Frequency reference

Input Frequency : 5 MHz or 10 MHz

 $Impedance \hspace{1.5cm} : 50\,\Omega$ 

Level :  $0 \text{ dBm} \pm 3 \text{ dB} (13 \text{ dBm max.})$ 

 $\begin{array}{ll} \text{Connector} & : \text{SMA Female} \\ \text{Output frequency: } 10 \text{ MHz} \\ \text{Impedance} & : 50 \, \Omega \\ \end{array}$ 

#### **Test IF output**

Number of outputs : 3 (according to Model)

Frequency output : 70 MHz

Output signal bandwidth : 5 MHz

Output impedance : 50  $\Omega$ Output VSWR :  $\leq$  1.5 dB

Output level :  $-30 \text{ dBm} \pm 2 \text{ dB}$ 

(regulated output, AGC ON)

Connector : SMA Female

**Remote Control** 

Link : RS232 and Ethernet

#### **Environmental Conditions**

Operating temperature  $: 10^{\circ} \text{ C to + 45}^{\circ} \text{ C}$ Transport and storage temperature  $: -30^{\circ} \text{ C to +70}^{\circ} \text{ C}$ 

Relative humidity : 95%







### **Tracking Down Converters for CTR70**

### Tracking Down Converter features

#### Input

Input frequency : S-Band 2.2 - 2.3 GHz

: C-Band 3.4 - 4.2 GHz / 4.8 GHz : X-Band 7.25 - 7.75 GHz

: X-Band 8.0 - 8.5 GHz : Ku-Band 10.0 - 12.75 GHz : Ka-Band : 17.7 – 21.2 GHz : Ka-Band : 25.5 – 27.0 GHz

Channels : 3 (depends on model)

 $\begin{array}{ll} \text{Impedance} & :50\,\Omega \\ \text{VSWR} & :\leq 1.5 \end{array}$ 

Connectors : depends on model

#### Output

 $\begin{array}{lll} \text{Output frequency} & : 70\text{MHz} \\ \text{Channels} & : 3 \\ \text{Impedance} & : 50\Omega \\ \text{VSWR} & : \leq 1.3 \\ \text{Connectors} & : \text{SMA Female} \\ \end{array}$ 

Differential Phase Gain : Autocalibration Correction

#### Reference

Input frequency : 5 or 10MHz (automatic detection)

 $\begin{array}{lll} \mbox{Impedance} & : 50 \Omega \\ \mbox{VSWR} & : \leq 1.3 \\ \mbox{Connector} & : \mbox{BNC Female} \\ \mbox{Dynamic range} & : 0 \mbox{ dBm +/-3 dB} \end{array}$ 

#### **Environmental Conditions**

Operating température :+10° Cto+45° C(Indoor Model) :-30° Cto+50° C(Outdoor Model)

#### Remote control

RS422 with dedicated CTR70 (DB9S)







### **Auto-Calibration**

- Auto-Calibration: This function provides the tracking chain with a long term stability on the differential phase & amplitude between channels.
   That is to say: you preserve your pointing accuracy in long term.
- Built-in inside tracking down-converter or external, auto-calibration is automatically managed by the tracking receiver.
- Auto-Calibration provides customers with a real advantage in term of quality and performances of tracking.







# **Monitoring & Control**

DTC and CTR Monitoring & Control commands

#### **DTC Commands**

Input frequency : yes
Channel Gain per channel : yes
Local / Remote : yes

#### **DTC Monitoring**

Channel Gain : Returned current value is monitored

#### Local / Remote

#### Remote control

DTC is 100% controlled and monitored through RS422 by CTR70 (DB9Sconnector)

#### **CTR70 Commands**

Input frequenc Sweep range

Sweep Centre

Polarity on each axis per Channel

Gain correction on each axis per Channel

Open loop

Offset voltage on each axis

Polarity, Offset and Slope on Automatic Gain Control

Acquisition threshold Anti-side band

Loop bandwidth Level Offset

Manual phase per Channel Phase step per chan<u>nel</u>

Tracking mode

Autophasing

Autocalibration and Autocal period

Error voltage integration time

Manual Gain

Tracking slope ratio

DTC attenuation per Channel

Autodiversity Threshold

Phasing external modulation: From O° to 359° with 1° step

Channel polarity 90° Output error type

#### **CTR70 Monitoring**

All mentioned commands and equipment status (lock , Unlock,, Output voltage value, alarm,...) are monitored.

#### Remote control

CTR70 is 100% controlled and monitored through RS232 or TCP/IP by the Antenna Control Unit and / or by external Laptop.







# How to perform a good tracking

### Reminders

- CTR70 is able to track :
  - Beacon carrier signals (with a carrier in coherent mode)
  - Suppressed carrier signals (AM/FM/QPSK/.../Spread Spectrum in no coherent mode).
- Minimum Signal / Noise density :
  - 8 dB in the loop bandwidth (coherent)
  - 3 dB above threshold (non coherent)
- Predicted Doppler value @ 70MHz must be included within the limits of CTR70 Sweep Range (SWR).
  - That is to say from  $\pm 1$  kHz to  $\pm 1500$  kHz with 1kHz steps.











# How to perform a good tracking

### Coherent Mode:

- 2BL Value, in coherent mode must be selected according to expected S/N ratio and maximum Doppler rate.
- Acquisition time in coherent mode optimization is done by adjusting the 2 following parameters: Sweep Range and Sweep Center Frequency.

### Non Coherent Mode:

In non Coherent Mode, the sole concern consists in having a received signal level **3dB above threshold** (input noise density level received on CTR70)







## Heritage

- More than 500 units have been sold worldwide for different purposes:
  - Antenna Manufacturers
  - Flight Test centers
  - Space Agencies
  - Space Prime contractors
  - Satellite Operators
- A range of products suited to worldwide customer requirements:
  - AIRBUS DEFENSE & Space, CNES, ECIL, ESA, ESOC, INEO, GLOBALSTAR, HAL, ISRO, ISTRAC, MT-MECHATRONIC, SSC, TELESPAZIO, THALES ALENIA Space, THALES, VERTEX, VIZADA, ...
- It is because our products suit your feed design with the best available pointing accuracy, that you don't have to customize your antenna system to our products!







## Thank your for your Attention